

## AQA A-Level Further Mathematics Warmup - Paper 1 2019

Define the exponential forms for the hyperbolic functions.	The quadratic equation $3x^2 + 10x + 5 = 0$ has roots $\alpha, \beta$ find the quadratic equation with roots $\frac{\alpha + 1}{2}, \frac{\beta + 1}{2}$ .	How can you convert a polar coordinate $(r, \theta)$ into cartesian coordinates?	For the 2nd order ODE $a \frac{d^2y}{dx^2} + b \frac{dy}{dx} + cy = 0$ describe how the discriminant of the auxiliary equation $am^2 + bm + c = 0$ determines the general solution.	State L'Hôpital's rule.
What are the $n$ th roots of unity?	Define the vector product for two vectors <b>a</b> and <b>b</b> .	What equation do the eigenvalues $\lambda$ , and eigenvectors <b>v</b> of the matrix <b>M</b> satisfy? How do you find eigenvalues?	State the modulus and argument form, and the exponential form of the complex number $z = a + ib$ .	What is the determinant and inverse of the $2 \times 2$ matrix $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ ?
Give the vector and cartesian equation of a line where <b>a</b> is a point on the line and <b>b</b> is the direction of the line.	What is $\sum_{i=1}^n r$ ?	Derive the logarithmic form of $\operatorname{arcosh}(x)$	State Viète's formulae for the cubic equation $ax^3 + bx^2 + cx + d = 0$ with roots $\alpha, \beta$ and $\gamma$ .	Describe how to find the inverse of a $3 \times 3$ matrix $M = \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$ .
How could you use quadratic theory to find the turning points of $y = \frac{2x^2 + 2x - 3}{x - 3}$ ?	What are the key properties of Simple Harmonic Motion (SHM)?	What is the mean value of the function $f(x)$ over the interval $[a, b]$ .	For the complex number $z = \cos(\theta) + i \sin(\theta)$ state the relations relating powers of $z$ and $\theta$ .	In the context of hyperbolic functions describe Osborn's rule and the affect this has on the identity $\cos^2(x) + \sin^2(x) = 1$
How do you diagonalise the matrix <b>M</b> ?	Give a suitable concluding statement for a proof by induction.	What is the difference between a line of invariant points and an invariant line for the matrix <b>M</b> ?	Define the scalar product for two vectors <b>a</b> and <b>b</b> .	How does the discriminant of the auxiliary equation for damped harmonic motion determine the type of damping?

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$\cosh(x) = \frac{e^x + e^{-x}}{2}$ $\sinh(x) = \frac{e^x - e^{-x}}{2}$ $\tanh(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}} = \frac{e^{2x} - 1}{e^{2x} + 1}$	<p>Use the substitution <math>x = 2w - 1</math> to obtain <math>12w^2 + 8w - 2</math>.</p>	<p>Use <math>x^2 + y^2 = r^2</math>,  <math>x = r \cos(\theta)</math>, <math>y = r \sin(\theta)</math>                      and <math>\tan(\theta) = \frac{y}{x}</math></p>	$b^2 - 4ac > 0$ , distinct real roots $\alpha, \beta$ so $y = Ae^{\alpha x} + Be^{\beta x}$ . $b^2 - 4ac = 0$ , repeated real root $\alpha$ so $y = (A + Bx)e^{\alpha x}$ . $b^2 - 4ac < 0$ , complex roots $p \pm qi$ so $y = e^{px}(A \cos(qx) + B \sin(qx))$	<p>If <math>\lim_{x \rightarrow c} f(x)</math> and <math>\lim_{x \rightarrow c} g(x)</math> are both zero or <math>\pm \infty</math> then</p> $\lim_{x \rightarrow c} \frac{f(x)}{g(x)} = \lim_{x \rightarrow c} \frac{f'(x)}{g'(x)}$
$\omega = e^{i \frac{2k\pi}{n}}$	$\mathbf{a} \times \mathbf{b} =  \mathbf{a}   \mathbf{b}  \sin(\theta) \hat{\mathbf{n}}$ $\mathbf{a} \times \mathbf{b} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$	$M\mathbf{v} = \lambda\mathbf{v}$ . Solve $\det(M - \lambda I) = 0$ .	$z = re^{i\theta}$ and $z = r(\cos(\theta) + i \sin(\theta))$ where $r$ is the modulus of $z$ and $\theta$ is its argument.	$\det(A) =  A  = ad - bc$ $A^{-1} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$
$\frac{\mathbf{r} - \mathbf{a} + \lambda \mathbf{b}}{x - a_1} = \frac{y - a_2}{b_1} = \frac{z - a_3}{b_2} = \frac{z - a_3}{b_3} = c$ <p>where <math>c</math> is a constant.</p>	$\sum_{i=1}^n r = \frac{1}{2}n(n+1)$	$\operatorname{arcosh}(x) = \ln(x + \sqrt{x^2 - 1})$	$\alpha + \beta + \gamma = \frac{-b}{a}$ $\alpha\beta + \alpha\gamma + \beta\gamma = \frac{c}{a}$ $\alpha\beta\gamma = -\frac{d}{a}$	<p>Find the determinant of the matrix. Find the matrix of minors <math>\begin{pmatrix} A &amp; B &amp; C \\ D &amp; E &amp; F \\ G &amp; H &amp; I \end{pmatrix}</math>, cofactors <math>\begin{pmatrix} A &amp; -B &amp; C \\ -D &amp; E &amp; -F \\ G &amp; -H &amp; I \end{pmatrix}</math>. Transpose this and multiply by the reciprocal of the determinant to get the inverse.</p>
<p>Set <math>k = \frac{2x^2 + 2x - 3}{x - 3}</math>, rearrange to form a quadratic and find the discriminant. Set equal to zero to find the y-coordinates of the turning points.</p>	$\ddot{x} = -\omega^2 x$ . Period $\frac{2\pi}{\omega}$ . The force acting on the object undergoing SHM is proportional to its displacement but in the opposite direction. The general solution $x = A \cos(\omega t) + B \sin(\omega t)$ can be rewritten in the form $x = R \cos(\omega t - \phi)$ .	$M = \frac{1}{b - a} \int_a^b f(x) dx$	$\frac{z^n + z^{-n}}{2} = \cos(n\theta)$ $2 \cos(n\theta) = z^n + \frac{1}{z^n}$ $\frac{z^n - z^{-n}}{2i} = \sin(n\theta)$ $z^n - \frac{1}{z^n} = 2i \sin(n\theta)$	<p>For every product or implied product of sines the sign is changed.</p> $\cosh^2(x) - \sinh^2(x) = 1$
<p>Find the eigenvalues and eigenvectors of the matrix. Then <math>M = UDU^{-1}</math> where <math>D</math> is a diagonal matrix containing the eigenvalues and <math>U</math> is a matrix whose columns are the (distinct) eigenvectors of <math>M</math>.</p>	<p>As the statement is true for <math>n = 1</math> and we have shown that if it holds for <math>n = k</math> then it also holds for <math>n = k + 1</math> we conclude that the statement must be true for all <math>n \geq 1</math> by the principle of mathematical induction.</p>	<p>Invariant points map to themselves under the action of <math>M</math>, so a line of invariant points is a line of such points.                      The image of any point on an invariant line remains on the line but is not necessarily the original point.</p>	$\mathbf{a} \cdot \mathbf{b} =  \mathbf{a}   \mathbf{b}  \cos(\theta)$ $\mathbf{a} \cdot \mathbf{b} = a_1 b_1 + a_2 b_2 + a_3 b_3$	<p>Discriminant less than zero means the system is lightly damped.                      Discriminant equal to zero means the system is critically damped.                      Discriminant greater than zero is heavily damped.</p>